

## EAST Search History

## EAST Search History (Prior Art)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	2	("4546293").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 09:41
L2	2	("4707650").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 09:44
L7	43	"736962"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 09:47
L8	2	("5789893").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 09:49
L9	4132	advance adj angle\$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 09:50
L10	10772740	control\$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 09:50
L11	2520889	correct\$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 09:50
L12	3807375	motor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 09:51
L13	8524942	position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 09:51

L14	698	I9 and I10 and I11 and I12 and I13	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 09:51
L16	116	I14 and predetermin \$3 and rotor and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 09:53
L22	1	speed\$1 and control \$3 and memory and rotor and motor and map and advance adj angle and correct\$3 adj factor and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 10:50
L24	3	speed\$1 and control \$3 and memory and rotor and motor and map and advance adj angle and angle near correct\$3 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 10:51
L25	4	("7007762").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 10:53
L26	25	("3908130"   "4072888"   "4316512"   "4455514"   "4546293"   "4633158"   "4641066"   "4922169"   "5115174"   "5287044"   "5298839"   "5360073"   "5589746"   "5637968"   "5701065"   "5982133"   "6134973"   "6239567"   "6424798"   "6536536"   "6538403").PN. OR ("7007762").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2010/04/19 10:53

L27	447737	control adj map\$4 or law	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:06
L28	1	27 and speed\$1 and control\$3 and memory and rotor and motor and advance adj angle and angle near correct\$3 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:06
L30	3	map\$4 and speed\$1 and control\$3 and memory and rotor and motor and advance adj angle and angle near correct\$3 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:17
L31	7	advance adj angle and correct\$3 adj factor and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:19
L38	0	control adj map and advance adj angle and angle adj correct\$3 and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:27
L44	963	(318/799).OCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 11:33
L45	0	44 and advance adj angle and correct\$3 adj factor and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:33
L46	0	44 and advance adj angle and angle near correct\$3 and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:33

L47	0	l44 and advance adj angle and angle adj correct\$3 and speed \$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:34
L48	0	l44 and advance adj angle and map\$4 and correct\$3 and speed \$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:34
L50	221	(318/437). CCLS	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 11:43
L51	0	l50 and advance adj angle and correct\$3 and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:44
L53	0	advance adj angle near memory and correct\$3 and speed \$1 and control\$3 and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:44
L54	8	advance adj angle near control\$3 and correct\$3 and speed \$1 and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:45
L55	2	advance adj angle and lead and lag near angle and speed\$1 and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:49
L56	14	advance adj angle and phase adj advance and correct\$3 and speed\$1 and rotor and motor and wind \$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:51

L57	144	(318/400.12).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 11:56
L58	0	57 and advance adj angle and phase adj advance and correct \$3 and speed\$1 and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:56
L59	0	57 and advance adj angle and correct\$3 and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:57
L60	0	57 and advance adj angle and map\$4 and correct\$3 and speed \$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:57
L61	0	57 and advance adj angle and angle adj correct\$3 and speed \$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:57
L62	749	(318/700).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 11:58
L63	0	62 and advance adj angle and angle adj correct\$3 and speed \$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:58
L64	0	62 and advance adj angle and correct\$3 and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:58

L73	2	("7443125").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:44
L74	3	("4168455").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:45
L75	2	("4611157").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:45
L76	2	("5012172").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:46
L77	2	("5206575").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:47
L78	2	("5450306").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:49
L79	2	("5640073").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:51
L80	2	("5903128").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:52
L81	2	("6072302").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:53

L82	61	" "6084786" "   "6128204" "   "6153956" "   "6166511" " "   "6201368" " "   "6222335" " "   "6288514" " "   "6313597" " "   "6316918" " "   "6380719" " "   "6486644" " "   "6490752" " "   "65" ("45443"   "6586904"   "6593720"   "6603672"   "6642681"   "6707265"   "6759826"   "6801441"   "6803739"   "6819008"   "6864658"   "6879062"   "6958589"   "7005828"   "7007762"   "7035123"   "7076830"   "7102903"   "7109605"   "7233873"   "7250734"   "7305569"   "7443125"   "RE40250")".PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 13:57
L83	0	82 and advance adj angle\$1 and correct\$3 and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 13:57
L84	0	82 and advance adj angle\$1 and control\$3 and memory and rotor and motor and wind \$4 and speed\$1 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 13:58
L85	0	82 and advance adj angle\$1 and control\$3 and memory and \$1otor and wind\$4 and speed\$1 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 13:58

L91	2	EP adj "129007"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 14:14
L92	0	EP adj "0505159"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 14:14
L93	2	EP adj "505159"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 14:15
L94	2	EP adj "748038"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 14:20
L105	276	(318/779).CCLS	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 15:25
L106	0	105 and advance adj angle\$1 and correct\$3 and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 15:25
L107	0	105 and advance adj angle\$1 and correct\$3 and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 15:26
L108	144	(318/400.12).CCLS	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 15:26
L109	0	108 and advance adj angle\$1 and correct\$3 and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 15:26



L110	749	(318/700).OCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 15:26
L111	0	1110 and advance adj angle\$1 and correct\$3 and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 15:27
S1	2	("4494055").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:35
S2	4	("4223258").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:36
S3	3	("4236102").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:37
S4	2	("4168455").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:37
S5	2	("4611157").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:38
S6	2	("4772839").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:39
S7	2	("5724477").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:39
S8	2	("6222335").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:47

S9	2	("5298839").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:48
S10	2	("5796226").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 11:39
S11	827	(318/701).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 11:39
S12	1352368	motor.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:39
S13	5036	SRM or switch\$2 adj reluctance.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:40
S14	9187760	control\$3 or ECU.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:40
S15	313182	rotor.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:40
S16	3892636	coil or phase or winding.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:41
S17	4197364	position\$3.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:41
S18	863815	map or table.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:41

S19	3563744	speed or torque.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:42
S20	1127926	angle.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:42
S21	10	S12 and S13 and S14 and S15 and S16 and S17 and S18 and S19 and S20	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:44
S22	3	vaccum adj motor.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/04 10:37
S23	26962	cleaning adj device. ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/04 10:36
S24	5036	SRM or switch\$2 adj reluctance.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/04 10:36
S25	1	S23 and S24	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/04 10:36
S26	437778	vacuum.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/04 10:38
S27	637565	clean\$3.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/04 10:38
S28	16	S24 and S26 and S27	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/04 10:38

S29	1	"10588289"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 14:21
S30	12	("4987546"   "5023527"   "5023528"   "5113125"   "5124625").PN. OR ("5796226").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2008/09/25 15:33
S31	445597	map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:56
S32	6269524	machine or motor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:57
S33	11237	(on or off) near angle	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:57
S34	17321	angle near correct\$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:57
S35	451	desir\$2 near power	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:58
S36	8644	(desir\$2 or actual) near power	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:58
S37	0	S31 and S32 and S33 and S34 and S36	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:59
S38	0	S31 and S32 and S33 and S34 and S35	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:59

S39	39	S31 and S32 and S33 and S34	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:59
S40	13	S39 and power and desir\$2	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 16:00
S41	6	"6819008"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/26 11:12
S42	5	predetermin\$3 and angle near correct\$3 and advanc\$2 near angle and rotor and stator and control\$3 and map\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 07:41
S43	12	("4987546"   "5023527"   "5023528"   "5113125"   "5124625").PN. OR ("5796226").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2009/03/03 08:00
S44	3	map\$4 and advance near angle near correct\$3 and rotor and stator and pole\$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 08:16
S45	5	map\$4 and advance near angle and angle near correct\$3 and rotor and stator and pole\$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 08:16
S46	42	map\$4 and angle near correct\$3 and rotor and stator and pole\$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 08:17
S47	13	("4942345"   "5446359"   "5461295"   "5532567"   "5589752"   "5652493"   "5767638"   "5796226"   "5814965"   "5864218").PN. OR ("6040678").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2009/03/03 09:04

S48	51	("3967173" "4739240" "4743815" "5140243" "5291115" "5448149" "5469039" "5475289" "5545964" "5563488" "5638265" "5677607" "5694010" "5705918" "5796226" "5841262" "5936386" "5969962" "6008601" "6011377" "6051942" "6150778" "6153993" "6157160" "6191676" "6285148" "6288514" "6472842" "6509710" "6593720" "6650082" "6683427" "6683428" "6707265" "6707266" "6710559" "6710564" "6724162" "6724168" "6734646" "6737820" "6747426" "6753663" "6756749" "6756757" "6762574" "6771035").PN. OR ("6819008").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2009/03/03 09:55
S49	10	("1292007").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 10:15

S50	844	(318/701).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 10:54
S51	1	S50 and map\$4 and advance near angle near correct\$3 and rotor and stator and pole\$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 10:54
S52	3	S50 and map\$4 and angle near correct\$3 and rotor and stator and pole\$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 10:55
S53	165	(318/712).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 11:12
S54	0	S53 and map\$4 and angle near correct\$3 and rotor and stator and pole\$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:12
S55	932	(318/799).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 11:12
S56	1	S55 and map\$4 and angle near correct\$3 and rotor and stator and pole\$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:13
S57	162	(318/715).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 11:22
S58	1	S57 and map\$4 and angle near correct\$3 and rotor and stator and pole\$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:22
S59	511	(318/721).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 11:24

S60	2	S59 and map\$4 and angle near correct\$3 and rotor and stator and pole\$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:24
S61	1	S59 and map\$4 and advance near angle and rotor and stator and pole\$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:32
S62	1602	(318/432).CQLS	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 11:34
S63	1	S62 and map\$4 and angle near correct\$3 and rotor and stator and pole\$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:34
S64	1	S62 and map\$4 and advance near angle and rotor and stator and pole\$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:34
S65	352	(318/433).CQLS	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 11:37
S66	1	S65 and map\$4 and advance near angle and rotor and stator and pole\$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:37
S67	711	(318/700).CQLS	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 11:39
S68	2	S67 and map\$4 and advance near angle and rotor and stator and pole\$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:39
S69	7	("4734633"   "5057759"   "5777447"   "6462492"   "6555988"   "6674261").PN. OR ("6803739").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2009/03/03 11:40



S70	14362926	one or single near angle near (correct\$3 or adjust\$4) same factor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 14:50
S71	1	S70 and motor and control adj map and energiz\$3 and turn near angle and predetermin\$3 and memory	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 14:52
S72	0	angle near factor and conduct\$3 near angle and turn near on	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 15:03
S73	0	correct\$3 near factor and conduct\$3 near angle and turn near on	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 15:03
S74	0	adjust\$4 near factor and conduct\$3 near angle\$1 and control near map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 15:04
S75	1	adjust\$4 near angle\$1 and factor and conduct\$3 near angle\$1 and control near map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 15:05
S76	0	correct\$3 near factor and conduct\$3 near angle\$1 and control near map and speed\$1 and rotor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 15:06
S77	0	adjust\$4 near factor and conduct\$3 near angle\$1 and control near map and speed\$1 and rotor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 15:06
S78	27	angle same factor and control near map and speed\$1 and rotor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 15:08
S79	2	("7443125").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:05

S80	2	switch\$2 near machine and angle near compensat\$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:09
S81	9	("5724477"   "6291949"   "6396237"   "6495985").PN. OR ("6586904").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2009/10/22 16:10
S82	3	switch\$2 near machine and angle near correct\$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:13
S83	856	(318/701).CQLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:13
S84	1	S83 and switch\$2 near machine and angle near correct\$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:14
S85	3568	(318/696).CQLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:14
S86	0	S85 and switch\$2 near machine and angle near correct\$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:14
S87	483	(318/400.01).CQLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:14
S88	0	S87 and switch\$2 near machine and angle near correct\$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:15
S89	202	(318/438).CQLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:15

S90	0	S89 and switch\$2 near machine and angle near correct\$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:15
S91	1053	318/799	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:16
S92	0	S91 and switch\$2 near machine and angle near correct\$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:16
S93	115	(318/290).CQLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:16
S94	0	S93 and switch\$2 near machine and angle near correct\$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:17
S95	1663	(318/432).CQLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:18
S96	0	S95 and switch\$2 near machine and angle near correct\$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:18
S97	524	(318/430).CQLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:18
S98	0	S97 and switch\$2 near machine and angle near correct\$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:18
S99	2	S91 and angle near correct\$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:19

S100	0	S91 and angle near adjust\$4 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:26
S101	0	S95 and angle near correct\$3 and rotor and speed and map and turn near on	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:27
S102	2	S95 and angle near correct\$3 and rotor and speed and map and control\$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:27
S103	219	(318/437).CQLS	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:27
S104	0	S103 and angle near correct\$3 and rotor and speed and map and control\$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:27
S105	136	angle near correct\$3 and rotor and speed and map and control \$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:28
S106	30	S105 and speed\$1 and rotor and predetermin\$3 near angle	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:29
S107	16	S106 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:29
S108	37	angle near correct\$3 and rotor and speed and map and control \$3 and motor with wind\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:33
S109	23	S108 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:33

S110	693	(173/217).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 17:26
S111	3	S110 and angle near correct\$3 and rotor and speed\$1 and map and control\$3 and map and motor with wind\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 17:26
S112	1	angle near correct\$3 and rotor and range near speed\$1 and map and control\$3 and motor with wind \$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 17:48
S113	1	angle near correct\$3 and rotor same range near speed\$1 and map and control\$3 and motor with wind \$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 17:49
S114	24	angle near correct\$3 and rotor same speeds and map and control\$3 and motor with wind\$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 17:50
S115	15	S114 and @py< = "2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 17:50
S120	24	("3908130"   "4072888"   "4316512"   "4455514"   "4546293"   "4633158"   "4641066"   "4922169"   "5115174"   "5287044"   "5298839"   "5360073"   "5589746"   "5637968"   "5701065"   "5982133"   "6134973"   "6239567"   "6424798"   "6536536"   "6538403").PN. OR ("7007762").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2009/12/03 12:04

S121	2	advance near angle and angle near correct \$3 and range near speed\$1 and rotor and motor and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/03 12:16
S122	20	advance near angle and angle near correct \$3 and speed\$1 and rotor and motor and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/03 12:16
S124	233	(318/400.23).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/12/04 12:12
S125	144	(318/400.12).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/12/04 12:13
S126	1	S124 and advance near angle and angle near correct\$3 and speed\$1 and rotor and motor and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/04 12:13
S127	0	S125 and advance near angle and angle near correct\$3 and speed\$1 and rotor and motor and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/04 12:13
S128	104	(318/400.32).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/12/04 12:14
S129	0	S128 and advance near angle and angle near correct\$3 and speed\$1 and rotor and motor and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/04 12:14
S130	858	(318/701).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/12/04 12:14
S131	1	S130 and advance near angle and angle near correct\$3 and speed\$1 and rotor and motor and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/04 12:14

## EAST Search History (Interference)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L18	63	speed\$1 and control\$3 and memory and advance adj angle near correct\$3 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 10:26
L19	2	speed\$1 and control\$3 and memory and rotor and motor and map and advance adj angle and angle adj correct\$3 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 10:48
L20	0	speed\$1 and control\$3 and memory and rotor and motor and map and advance adj angle and angle near correct\$3 adj factor and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 10:49
L21	1	speed\$1 and control\$3 and memory and rotor and motor and map and advance adj angle and correct\$3 adj factor and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 10:49
L32	6	advance adj angle and correct\$3 adj factor and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:19
L34	1	angle near map\$4 and correct\$3 adj factor and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:26
L35	0	on near advance adj angle and map\$4 and correct\$3 adj factor and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:26
L39	0	control adj map and advance adj angle and angle adj correct\$3 and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:28

L41	0	control adj table\$1 and advance adj angle and angle adj correct\$3 and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:29
L42	0	control adj table\$1 and advance adj angle and angle near correct\$3 and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:29
L43	1	table\$1 and advance adj angle and angle near correct\$3 and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:29
L49	45	("4223261"   "4429262"   "4447771"   "4490661"   "4498037").PN. OR ("4651068").URPN.	US-PGPUB; USPAT	OR	ON	2010/04/19 11:35
L52	0	advance adj angle near memory and correct\$3 and speed\$1 and control \$3 and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:44
L65	0	advance adj angle adj profile and correct\$3 and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:58
L66	0	advance adj angle adj profile and correct\$3 adj factor and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:58
L67	2	advance adj angle and profile and correct\$3 adj factor and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:59



L68	0	advance adj angle and profile and conduct\$3 adj angle\$1 and correct\$3 and speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 12:00
L69	3	advance adj angle and conduct\$3 adj angle\$1 and correct\$3 and speed \$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 12:00
L70	19	advance adj angle and range near speed\$1 and control\$3 and memory and rotor and motor and wind\$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 12:10
L71	63	("4270074"   "4368411"   "4489267"   "4602882"). PN. OR ("4739240"). URPN.	US-PGPUB; USPAT	OR	ON	2010/04/19 12:31
L72	2	correct\$3 adj factor near advance adj angle\$1 and motor	US-PGPUB; USPAT	OR	ON	2010/04/19 13:07
L86	1	correct\$3 near advance adj angle\$1 and control\$3 and memory and \$1otor and wind\$4 and speed\$1 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 13:59
S116	0	correct\$3 near factor and conduct\$3 near angle and turn near on	USPAT; UPAD	OR	ON	2009/10/22 15:04
S117	0	correct\$3 near angle\$1 and control near map and speed\$1 and rotor and conduct\$3	USPAT; UPAD	OR	ON	2009/10/22 16:08
S118	0	adjust\$3 near angle\$1 and control near map and speed\$1 and rotor and conduct\$3	USPAT; UPAD	OR	ON	2009/10/22 16:08
S119	0	switch\$2 near machine and angle near compensat \$3 and rotor and speed and map	USPAT; UPAD	OR	ON	2009/10/22 16:09
S123	1	advance near angle and angle near correct\$3 and range near speed\$1 and rotor and motor and map	USPAT; UPAD	OR	ON	2009/12/03 12:15

S132	9	advance near angle and angle near correct\$3 and speed\$1 and rotor and motor and map	USPAT; UPAD	OR	ON	2009/12/04 12:15
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**4/ 19/ 2010 3:27:54 PM****C:\ Documents and Settings\ apaul\ My Documents\ EAST\ Workspaces\ 10588289.wsp**